

Cutting-Edge Techniques for Depth Map Super-Resolution

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Outline

1. Depth Map Super-Resolution

2. Methods

- Shifted **Window** (Swin) Transformer, **Nonlinear Activation Free** (NAF) Networks, **Deformable Kernel Networks** (DKN)

3. Proposed Architectures

- Swin Transformer- and NAF-based **Depth Map Super Resolution** (DMSR)

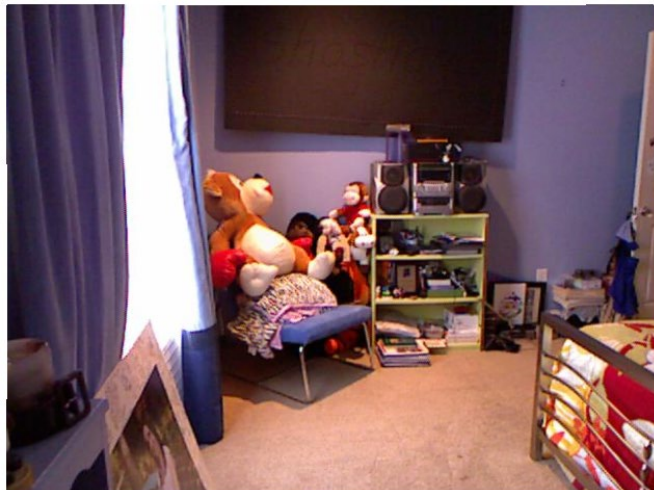
4. Results and Conclusions



Depth Map Super-Resolution

- Input:

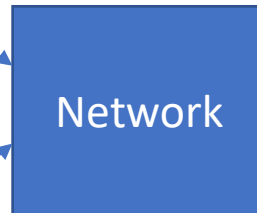
- High-resolution RGB image
- Low-resolution depth image



H, W, C



H/8, W/8, 1



- Output:

- High-resolution depth image

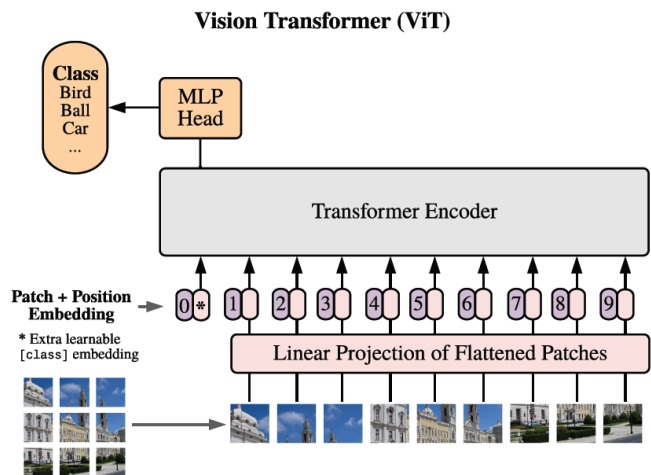


H, W, 1

Swin Transformer Architecture

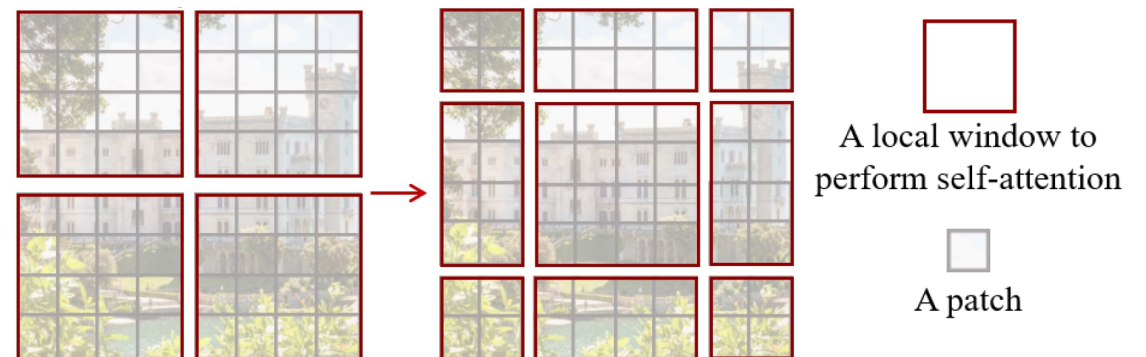
Vision Transformer (ViT)

- Split image into patches
- Use MSA encoder-decoder
- Global context, translationally variant



Swin Transformer

- Hierarchical (different patch sizes)
- Local self-attention
- Shifting windows \rightarrow translationally equivariant (CNN), local context

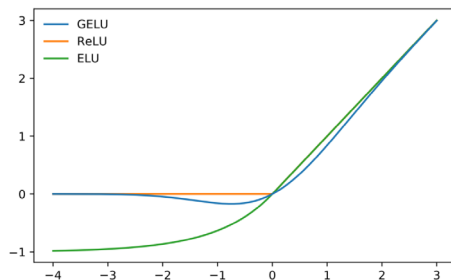


Nonlinear Activation Free (NAF) Networks

Nonlinear Activation Functions

- GELU

$$\text{GELU}(x) = x \odot \phi(x)$$

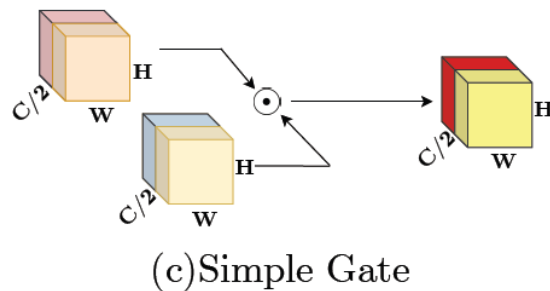


- Gated Linear Unit (GLU)

$$\text{GLU}(x) = f(x) \odot \sigma(g(x))$$

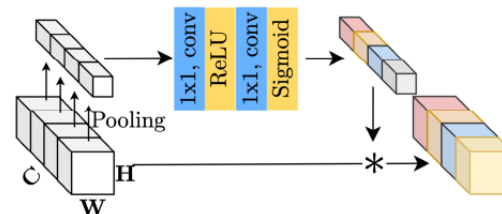
- SimpleGate (SG)

$$\text{SG}(x, y) = x \odot y$$

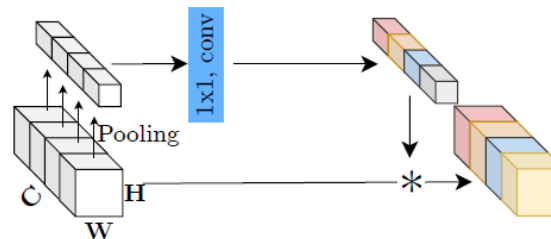


Simplified Channel Attention

- Channel attention

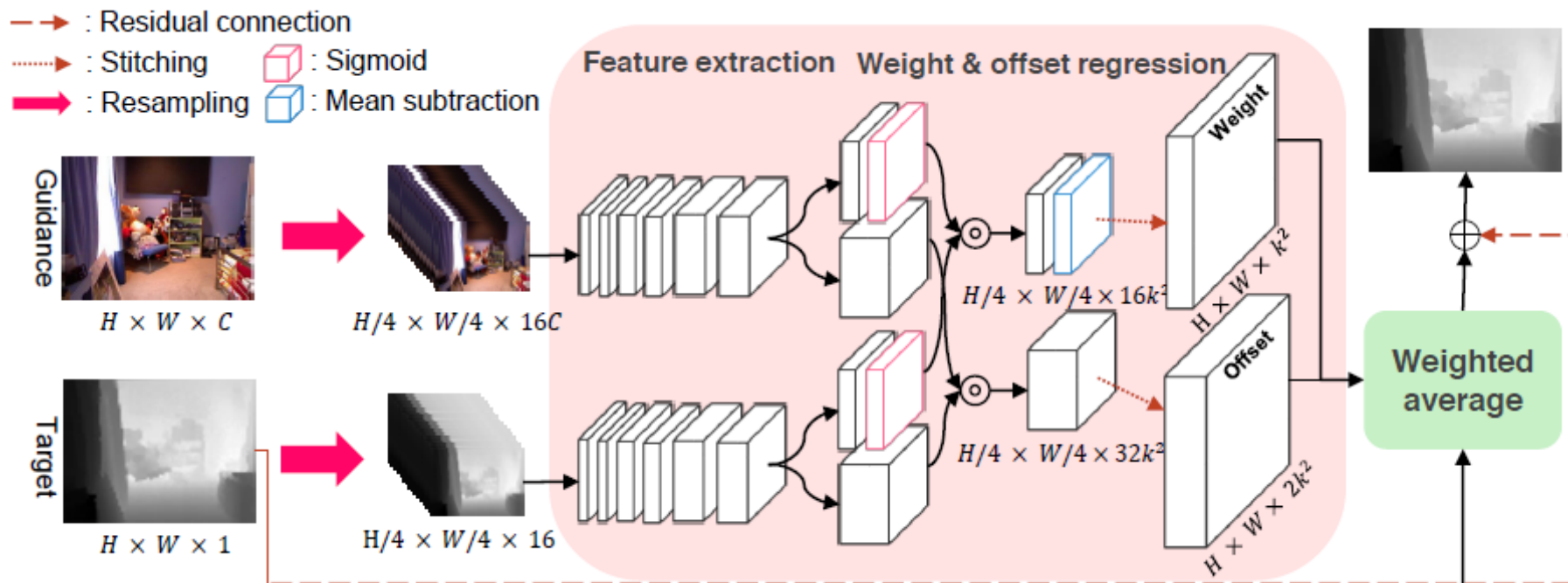


- Simplified Channel Attention



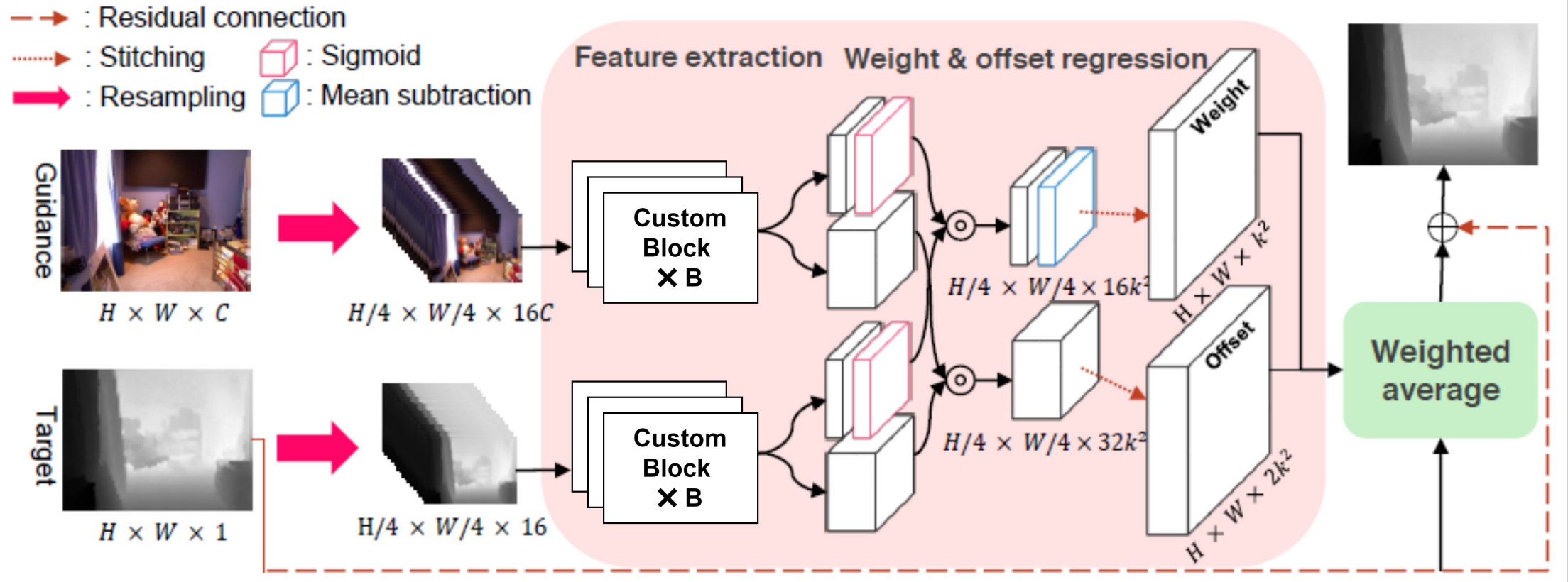
Deformable Kernel Networks (DKN)

- Images are resampled
- Features from each image are extracted
- Combined
- Stitched
- Averaged with original depth



Our Networks

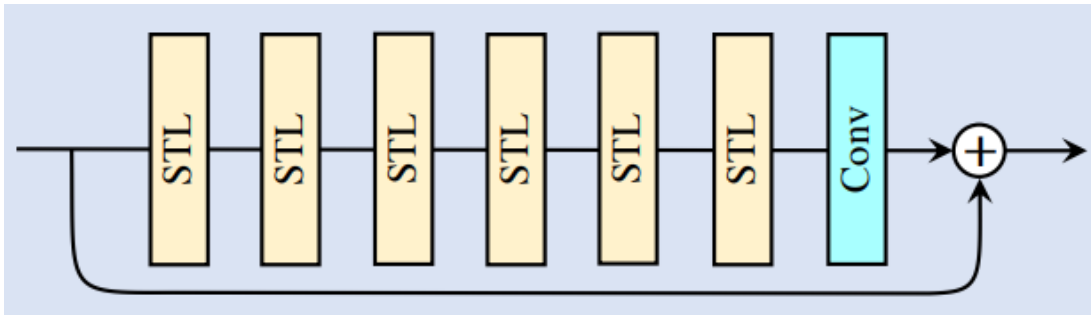
1. Swin transformer-based blocks
2. NAF-based blocks



Custom Network Architecture

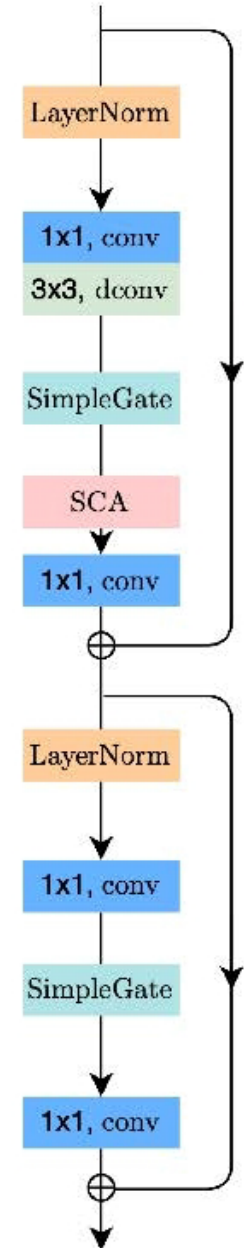
Residual Swin Transformer Block (RSTB)

- Sequential Swin layers
- Residual connection

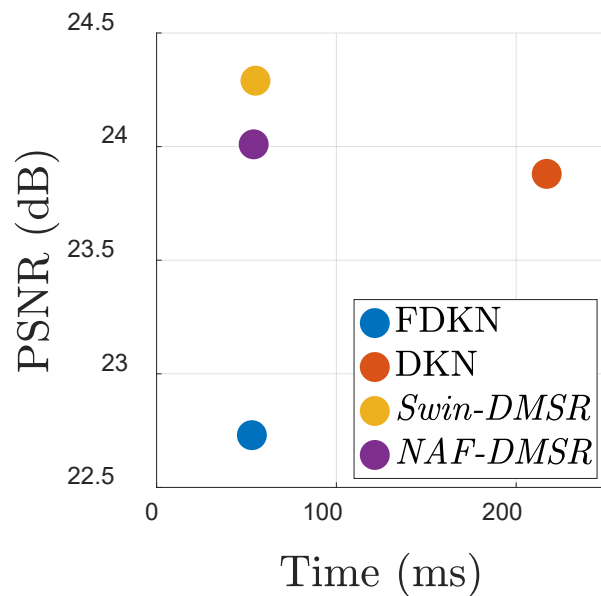
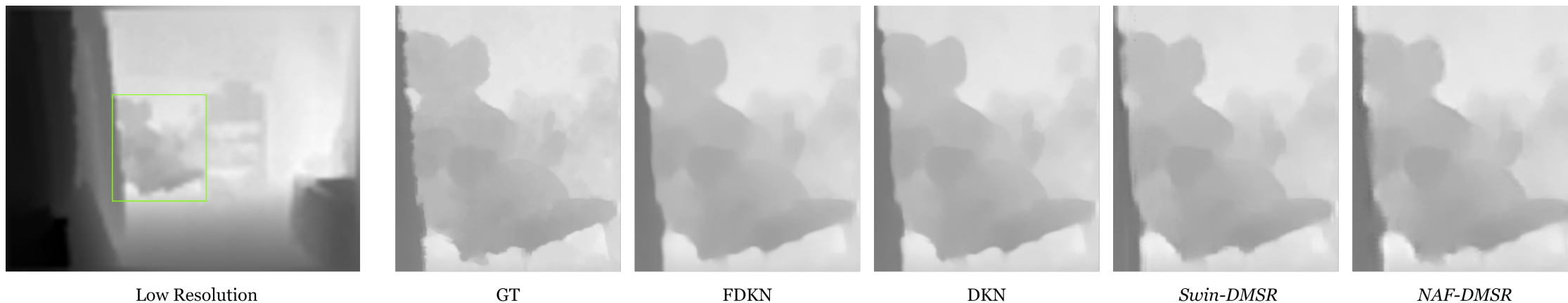


NAF Block

- Simplified in comparison to state-of-the-art blocks
- Uses convolution and attention



Results



	FDKN	DKN	<i>Swin-DMSR</i>	<i>NAF-DMSR</i>
PSNR (dB)	22.73	23.88	24.29	24.01
Time (ms)	53	217	55	54

Questions?

