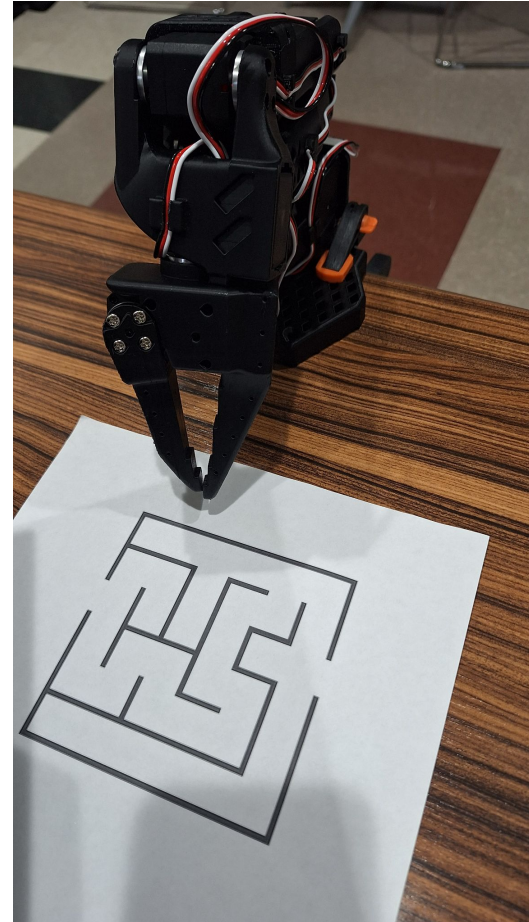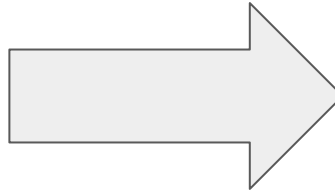# Robomaze
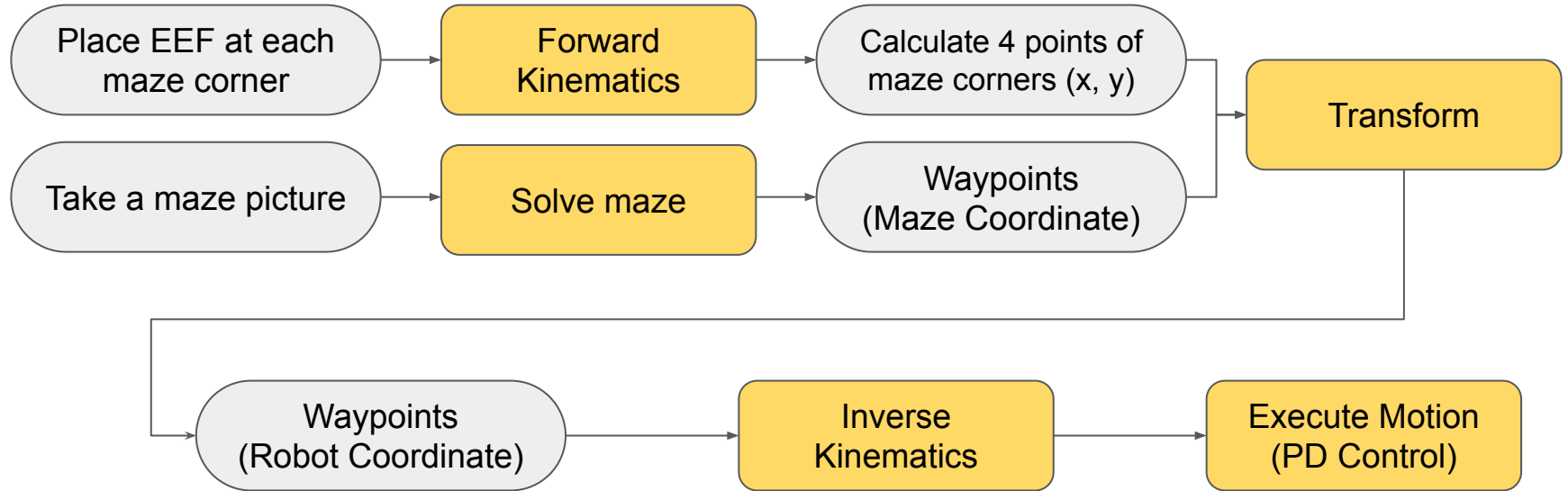
Eun Yeo / Jaehyun Park / Joel Flores / Muil Yang

Goal
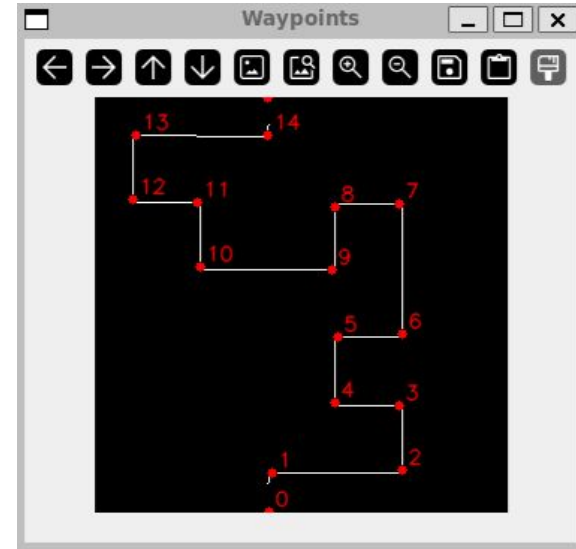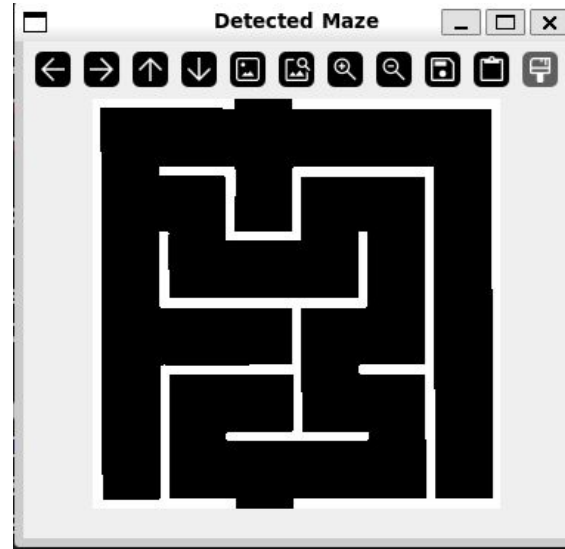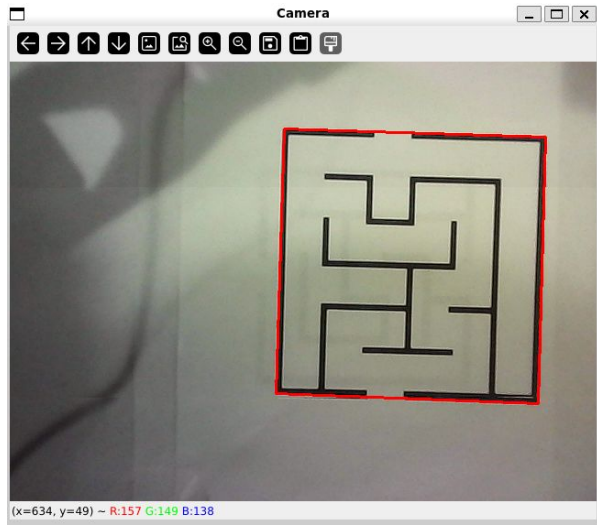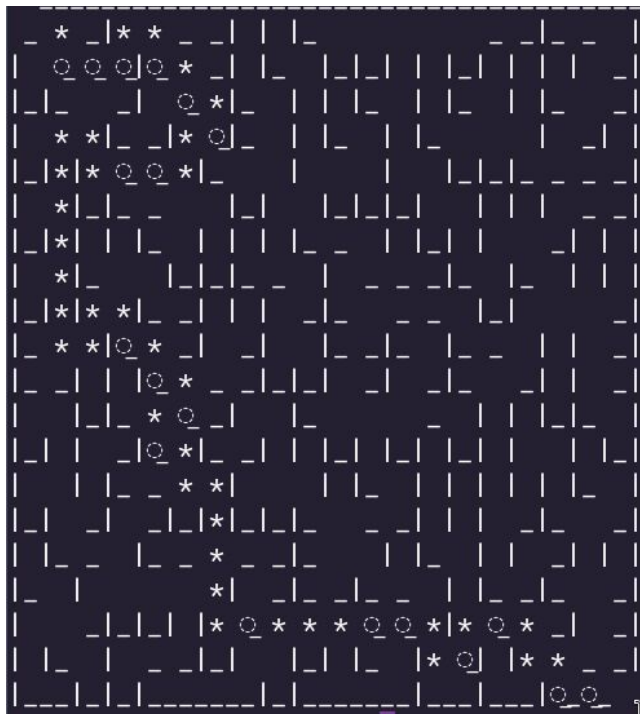
Workflow

Vision

Maze Solve

- Convert maze to a binary grid (wall, paths)
- Find entrance/exit
- Run a graph search to get a path
- Return waypoints

Motion Execution